

BRUSHLESS MOTOR  
**TKA202HS**  
 ELECTRONIC DRIVE  
**Drive 20/100 Arms**



No UL certification

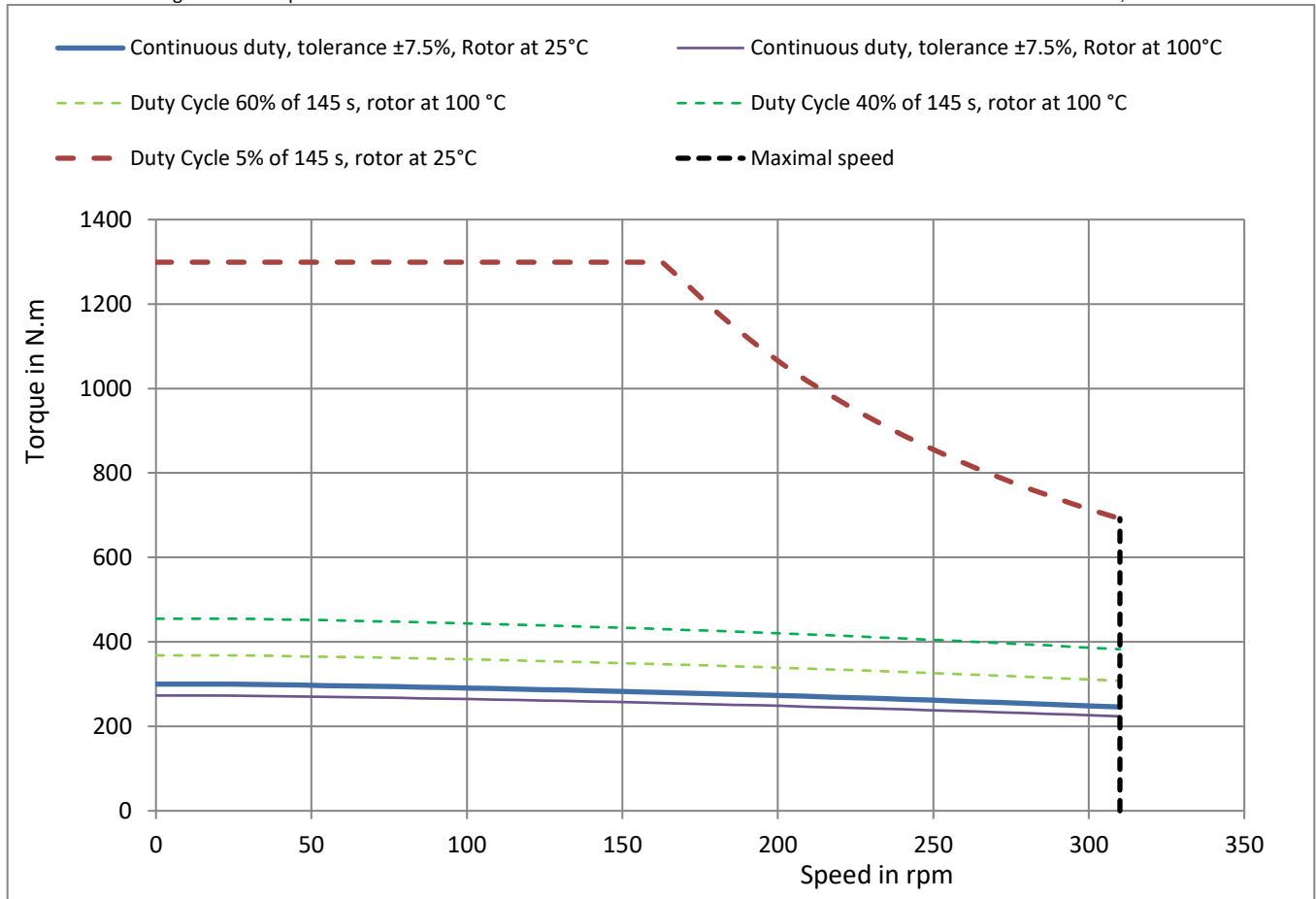
P <sub>n</sub>	<b>Rated power **</b>	7.98	<i>kW</i>	<b>Cooling type :</b> Natural Air Cooling Exchange Surface 0.44 m <sup>2</sup>
M <sub>n</sub>	<b>Rated torque **</b>	246	<i>Nm</i>	
N <sub>n</sub>	<b>Rated speed</b>	310	<i>rpm</i>	
I <sub>n</sub>	<b>Rated current</b>	15.1	<i>A<sub>rms</sub></i>	
U <sub>n</sub>	<b>Rated voltage *</b>	342	<i>V<sub>rms</sub></i>	
U <sub>R</sub>	<b>Voltage of the mains</b>	400	<i>V<sub>rms</sub></i>	
U	DC voltage supply when motor is loaded	540	<i>V</i>	
M <sub>o</sub>	<b>Low speed torque **</b>	300	<i>N.m</i>	<b>Environment :</b> Ambient temperature : 40°C MAX Altitude : < 1000 m Thermal class : F (according to IEC 60034-1)
I <sub>o</sub>	<b>Permanent current at low speed</b>	17.8	<i>A<sub>rms</sub></i>	
M <sub>p</sub>	Max. torque **	1300	<i>Nm</i>	
I <sub>p</sub>	Max. current	99.5	<i>A<sub>rms</sub></i>	
N <sub>p</sub>	Max. speed	310	<i>rpm</i>	
J	Rotor inertia	0.18	<i>kg.m<sup>2</sup></i>	Number of poles : 60 Electrical frequency @N <sub>p</sub> 155 Hz
K <sub>e</sub>	Back emf constant at 1000 rpm (25°C)*	1090	<i>V<sub>rms</sub></i>	
K <sub>t</sub>	Torque sensitivity (rotor 25°C)	16.8	<i>Nm/A<sub>rms</sub></i>	<b>Efficiency :</b> at rated torque : 90.7 % at 75% of rated torque : 91.4 %
R <sub>b</sub>	Winding resistance(25°C) *	1.14	<i>Ω</i>	
L	Winding inductance *	9.02	<i>mH</i>	

All data are given in typical values under standard conditions.

\* Phase to Phase

Characteristics are given for an optimal drive of the motor.

\*\* General tolerances ±7.5 %, rotor at 25°C





No UL certification

### Main characteristics

Rated power **	7.98	kW	Ps1
Peak power **	22.5	kW	Ps6
Low speed torque **	300	N.m	Mo
Low speed peak torque **	1300	N.m	MoS6
Nominal speed (S1)	310	rpm	Nb
Max speed ****	310	rpm	Nmax
DC voltage supply when motor is loaded	540	Vdc	Ū
Permanent current at low speed	17.8	Arms	Io
S6 current at low speed	99.5	Arms	IoS6

### Mechanical parameters

Rotor inertia	0.18	kg.m <sup>2</sup>	J
Motor mass	--	kg	M
Maximum speed with Drive	310	rpm	Nmax
Maximum mechanical speed	-	rpm	Nmec

### Electrical parameters

Number of poles	60		
Winding resistance (25°C) *	1.14	Ω	Rb
Back EMF voltage/ 1000 rpm *	1090	Vrms / 1000 rpm	ke
Back EMF voltage / (rad/s) *	10.4	Vrms / (rad/s)	ku
Torque constant	16.8	N.m / Arms	Kt
Short circuit current	43.8	Arms	Icc
Inductance Lq (Back EMF voltage axis) *	9.02	mH	Lq
Inductance Ld *	9.15	mH	Ld
Optimal phasing at permanent current	10	electrical degree	ψo
Optimal phasing at S6 current	20	electrical degree	ψm

### Thermal parameters

Motor thermal resistance	0.135	K/W	Rth
Motor thermal time constant	--	s	Tth
Winding thermal time constant	370	s	Tthw
Natural Air Cooling / Exchange Surface	0.44 m <sup>2</sup>		

Thermal class according to IEC 60034-1

F

\* Phase to phase

\*\* Tolerances ± 7.5% and rotor at 25°C

BRUSHLESS MOTOR  
**TKA204HV**  
 ELECTRONIC DRIVE  
**Drive 25/122 Arms**



No UL certification

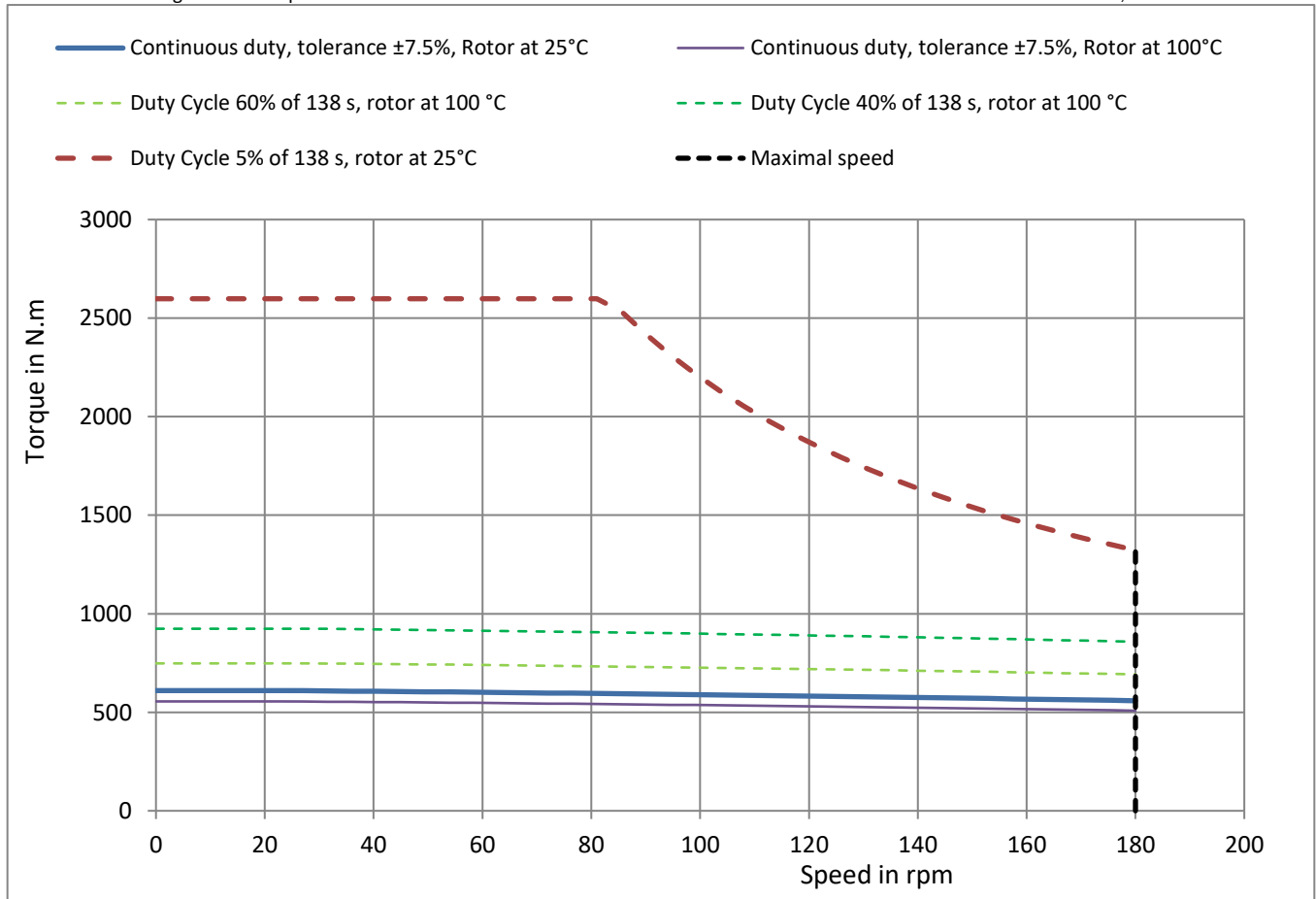
P <sub>n</sub>	<b>Rated power **</b>	10.5	<i>kW</i>	<b>Cooling type :</b> Natural Air Cooling Exchange Surface 0.82 m <sup>2</sup>
M <sub>n</sub>	<b>Rated torque **</b>	558	<i>Nm</i>	
N <sub>n</sub>	<b>Rated speed</b>	180	<i>rpm</i>	
I <sub>n</sub>	<b>Rated current</b>	20.7	<i>A<sub>rms</sub></i>	
U <sub>n</sub>	<b>Rated voltage *</b>	342	<i>V<sub>rms</sub></i>	
U <sub>R</sub>	<b>Voltage of the mains</b>	400	<i>V<sub>rms</sub></i>	
U	DC voltage supply when motor is loaded	540	<i>V</i>	
M <sub>o</sub>	<b>Low speed torque **</b>	610	<i>N.m</i>	<b>Environment :</b> Ambient temperature : 40°C MAX Altitude : < 1000 m Thermal class : F (according to IEC 60034-1)
I <sub>o</sub>	<b>Permanent current at low speed</b>	22.2	<i>A<sub>rms</sub></i>	
M <sub>p</sub>	Max. torque **	2600	<i>Nm</i>	
I <sub>p</sub>	Max. current	122	<i>A<sub>rms</sub></i>	
N <sub>p</sub>	Max. speed	180	<i>rpm</i>	
J	Rotor inertia	0.35	<i>kg.m<sup>2</sup></i>	Number of poles : 60 Electrical frequency @N <sub>p</sub> 90 Hz
K <sub>e</sub>	Back emf constant at 1000 rpm (25°C)*	1780	<i>V<sub>rms</sub></i>	
K <sub>t</sub>	Torque sensitivity (rotor 25°C)	27.4	<i>Nm/A<sub>rms</sub></i>	<b>Efficiency :</b> at rated torque : 87.6 % at 75% of rated torque : 89.9 %
R <sub>b</sub>	Winding resistance(25°C) *	1.35	<i>Ω</i>	
L	Winding inductance *	11.9	<i>mH</i>	

All data are given in typical values under standard conditions.

\* Phase to Phase

Characteristics are given for an optimal drive of the motor.

\*\* General tolerances ±7.5 %, rotor at 25°C





No UL certification

### Main characteristics

Rated power **	10.5	kW	Ps1
Peak power **	24.9	kW	Ps6
Low speed torque **	610	N.m	Mo
Low speed peak torque **	2600	N.m	MoS6
Nominal speed (S1)	180	rpm	Nb
Max speed ****	180	rpm	Nmax
DC voltage supply when motor is loaded	540	Vdc	Ū
Permanent current at low speed	22.2	Arms	Io
S6 current at low speed	122	Arms	IoS6

### Mechanical parameters

Rotor inertia	0.35	kg.m <sup>2</sup>	J
Motor mass	--	kg	M
Maximum speed with Drive	180	rpm	Nmax
Maximum mechanical speed	-	rpm	Nmec

### Electrical parameters

Number of poles	60		
Winding resistance (25°C) *	1.35	Ω	Rb
Back EMF voltage/ 1000 rpm *	1780	Vrms / 1000 rpm	ke
Back EMF voltage / (rad/s) *	17	Vrms / (rad/s)	ku
Torque constant	27.4	N.m / Arms	Kt
Short circuit current	54	Arms	Icc
Inductance Lq (Back EMF voltage axis) *	11.9	mH	Lq
Inductance Ld *	12.1	mH	Ld
Optimal phasing at permanent current	10	electrical degree	ψo
Optimal phasing at S6 current	20	electrical degree	ψm

### Thermal parameters

Motor thermal resistance	0.0745	K/W	Rth
Motor thermal time constant	--	s	Tth
Winding thermal time constant	350	s	Tthw
Natural Air Cooling / Exchange Surface	0.82 m <sup>2</sup>		

Thermal class according to IEC 60034-1

F

\* Phase to phase

\*\* Tolerances ± 7.5% and rotor at 25°C

BRUSHLESS MOTOR  
**TKA206HS**  
 ELECTRONIC DRIVE  
**Drive 40/195 Arms**



No UL certification

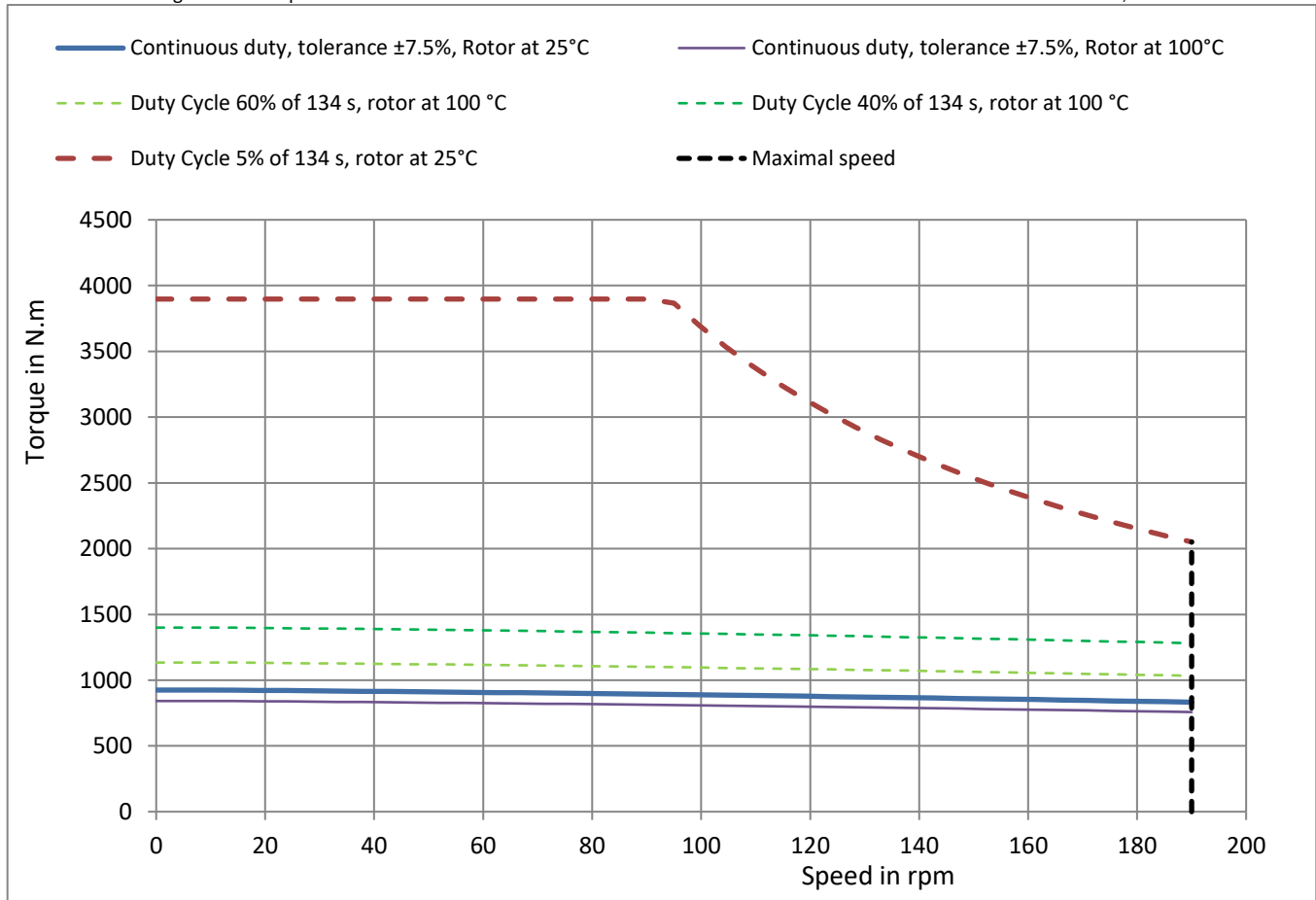
P <sub>n</sub>	<b>Rated power **</b>	16.6	<i>kW</i>	<b>Cooling type :</b> Natural Air Cooling Exchange Surface 1.2 m <sup>2</sup>
M <sub>n</sub>	<b>Rated torque **</b>	832	<i>Nm</i>	
N <sub>n</sub>	<b>Rated speed</b>	190	<i>rpm</i>	
I <sub>n</sub>	<b>Rated current</b>	32.7	<i>A<sub>rms</sub></i>	
U <sub>n</sub>	<b>Rated voltage *</b>	338	<i>V<sub>rms</sub></i>	
UR	<b>Voltage of the mains</b>	400	<i>V<sub>rms</sub></i>	
U	DC voltage supply when motor is loaded	540	<i>V</i>	
M <sub>o</sub>	<b>Low speed torque **</b>	925	<i>N.m</i>	<b>Environment :</b> Ambient temperature : 40°C MAX Altitude : < 1000 m Thermal class : F (according to IEC 60034-1)
I <sub>o</sub>	<b>Permanent current at low speed</b>	35.7	<i>A<sub>rms</sub></i>	
M <sub>p</sub>	Max. torque **	3900	<i>Nm</i>	
I <sub>p</sub>	Max. current	195	<i>A<sub>rms</sub></i>	
N <sub>p</sub>	Max. speed	190	<i>rpm</i>	
J	Rotor inertia	0.52	<i>kg.m<sup>2</sup></i>	Number of poles : 60 Electrical frequency @N <sub>p</sub> 95 Hz
Ke	Back emf constant at 1000 rpm (25°C)*	1670	<i>V<sub>rms</sub></i>	
Kt	Torque sensitivity (rotor 25°C)	25.9	<i>Nm/A<sub>rms</sub></i>	<b>Efficiency :</b> at rated torque : 88.3 % at 75% of rated torque : 90.3 %
R <sub>b</sub>	Winding resistance(25°C) *	0.779	<i>Ω</i>	
L	Winding inductance *	7.08	<i>mH</i>	

All data are given in typical values under standard conditions.

\* Phase to Phase

Characteristics are given for an optimal drive of the motor.

\*\* General tolerances ±7.5 %, rotor at 25°C





No UL certification

### Main characteristics

Rated power **	16.6	kW	Ps1
Peak power **	40.8	kW	Ps6
Low speed torque **	925	N.m	Mo
Low speed peak torque **	3900	N.m	MoS6
Nominal speed (S1)	190	rpm	Nb
Max speed ****	190	rpm	Nmax
DC voltage supply when motor is loaded	540	Vdc	Ū
Permanent current at low speed	35.7	Arms	Io
S6 current at low speed	195	Arms	IoS6

### Mechanical parameters

Rotor inertia	0.52	kg.m <sup>2</sup>	J
Motor mass	--	kg	M
Maximum speed with Drive	190	rpm	Nmax
Maximum mechanical speed	-	rpm	Nmec

### Electrical parameters

Number of poles	60		
Winding resistance (25°C) *	0.779	Ω	Rb
Back EMF voltage/ 1000 rpm *	1670	Vrms / 1000 rpm	ke
Back EMF voltage / (rad/s) *	15.9	Vrms / (rad/s)	ku
Torque constant	25.9	N.m / Arms	Kt
Short circuit current	85.9	Arms	Icc
Inductance Lq (Back EMF voltage axis) *	7.08	mH	Lq
Inductance Ld *	7.16	mH	Ld
Optimal phasing at permanent current	10	electrical degree	ψo
Optimal phasing at S6 current	20	electrical degree	ψm

### Thermal parameters

Motor thermal resistance	0.0514	K/W	Rth
Motor thermal time constant	--	s	Tth
Winding thermal time constant	340	s	Tthw
Natural Air Cooling / Exchange Surface	1.2 m <sup>2</sup>		

Thermal class according to IEC 60034-1

F

\* Phase to phase

\*\* Tolerances ± 7.5% and rotor at 25°C

BRUSHLESS MOTOR  
**TKA302HP**  
 ELECTRONIC DRIVE  
**Drive 25/86 Arms**



No UL certification

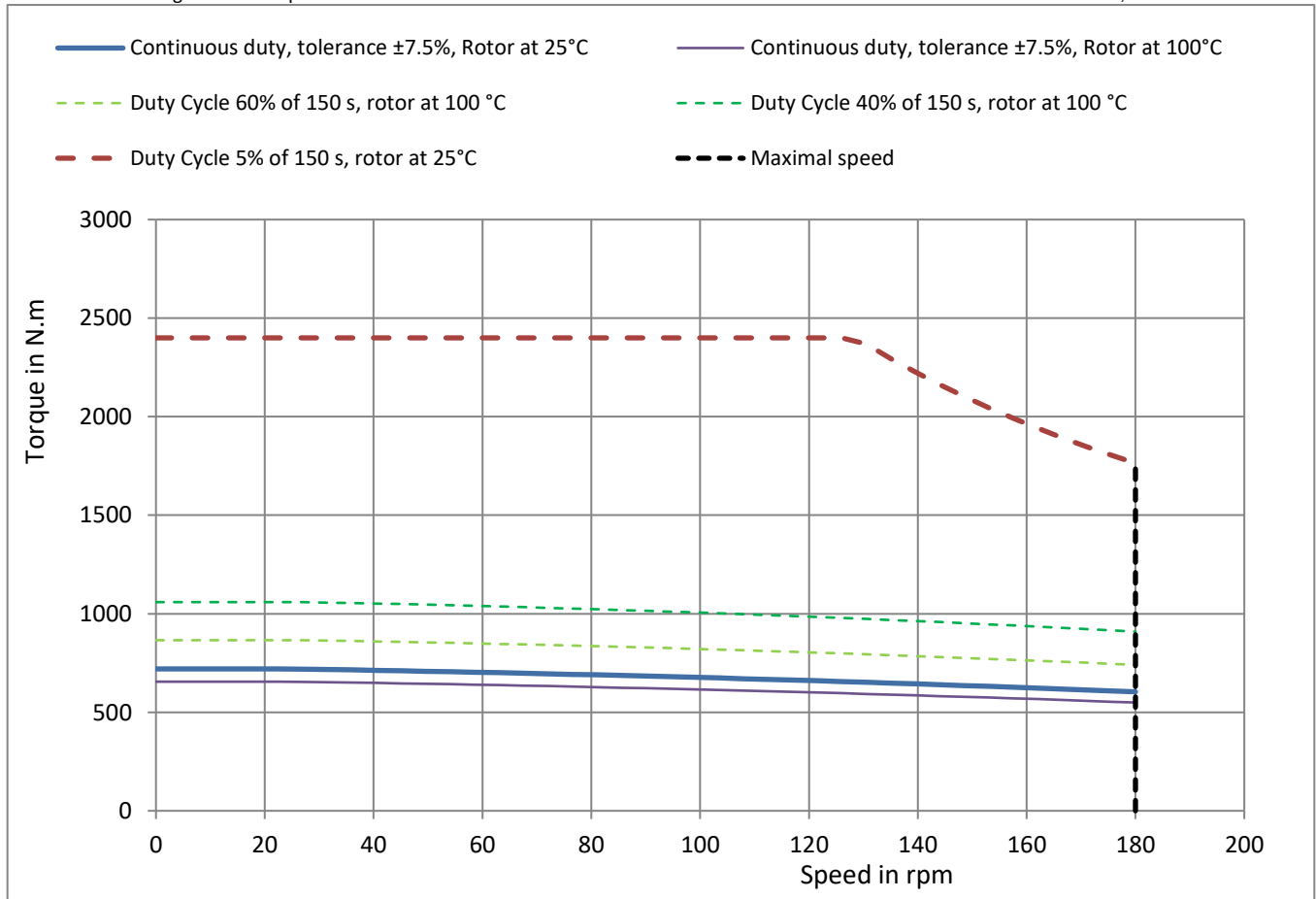
P <sub>n</sub>	<b>Rated power **</b>	11.4	<i>kW</i>	<b>Cooling type :</b> Natural Air Cooling Exchange Surface 0.64 m <sup>2</sup>
M <sub>n</sub>	<b>Rated torque **</b>	604	<i>Nm</i>	
N <sub>n</sub>	<b>Rated speed</b>	180	<i>rpm</i>	
I <sub>n</sub>	<b>Rated current</b>	20.5	<i>A<sub>rms</sub></i>	
U <sub>n</sub>	<b>Rated voltage *</b>	355	<i>V<sub>rms</sub></i>	
U <sub>R</sub>	<b>Voltage of the mains</b>	400	<i>V<sub>rms</sub></i>	
U	DC voltage supply when motor is loaded	540	<i>V</i>	
M <sub>o</sub>	<b>Low speed torque **</b>	720	<i>N.m</i>	<b>Environment :</b> Ambient temperature : 40°C MAX Altitude : < 1000 m Thermal class : F (according to IEC 60034-1)
I <sub>o</sub>	<b>Permanent current at low speed</b>	24	<i>A<sub>rms</sub></i>	
M <sub>p</sub>	Max. torque **	2400	<i>Nm</i>	
I <sub>p</sub>	Max. current	85.9	<i>A<sub>rms</sub></i>	
N <sub>p</sub>	Max. speed	180	<i>rpm</i>	
J	Rotor inertia	1.2	<i>kg.m<sup>2</sup></i>	Number of poles : 90 Electrical frequency @N <sub>p</sub> 135 Hz
K <sub>e</sub>	Back emf constant at 1000 rpm (25°C)*	1880	<i>V<sub>rms</sub></i>	
K <sub>t</sub>	Torque sensitivity (rotor 25°C)	30	<i>Nm/A<sub>rms</sub></i>	<b>Efficiency :</b> at rated torque : 90.9 % at 75% of rated torque : 91.6 %
R <sub>b</sub>	Winding resistance(25°C) *	0.88	<i>Ω</i>	
L	Winding inductance *	6.58	<i>mH</i>	

All data are given in typical values under standard conditions.

\* Phase to Phase

Characteristics are given for an optimal drive of the motor.

\*\* General tolerances ±7.5 %, rotor at 25°C





No UL certification

### Main characteristics

Rated power **	11.4	kW	Ps1
Peak power **	33.3	kW	Ps6
Low speed torque **	720	N.m	Mo
Low speed peak torque **	2400	N.m	MoS6
Nominal speed (S1)	180	rpm	Nb
Max speed ****	180	rpm	Nmax
DC voltage supply when motor is loaded	540	Vdc	Ū
Permanent current at low speed	24	Arms	Io
S6 current at low speed	85.9	Arms	IoS6

### Mechanical parameters

Rotor inertia	1.2	kg.m <sup>2</sup>	J
Motor mass	--	kg	M
Maximum speed with Drive	180	rpm	Nmax
Maximum mechanical speed	-	rpm	Nmec

### Electrical parameters

Number of poles	90		
Winding resistance (25°C) *	0.88	Ω	Rb
Back EMF voltage/ 1000 rpm *	1880	Vrms / 1000 rpm	ke
Back EMF voltage / (rad/s) *	18	Vrms / (rad/s)	ku
Torque constant	30	N.m / Arms	Kt
Short circuit current	68.8	Arms	Icc
Inductance Lq (Back EMF voltage axis) *	6.58	mH	Lq
Inductance Ld *	6.71	mH	Ld
Optimal phasing at permanent current	10	electrical degree	ψo
Optimal phasing at S6 current	20	electrical degree	ψm

### Thermal parameters

Motor thermal resistance	0.0903	K/W	Rth
Motor thermal time constant	--	s	Tth
Winding thermal time constant	380	s	Tthw
Natural Air Cooling / Exchange Surface	0.64 m <sup>2</sup>		

Thermal class according to IEC 60034-1

F

\* Phase to phase

\*\* Tolerances ± 7.5% and rotor at 25°C



BRUSHLESS MOTOR  
**TKA304HN**  
 ELECTRONIC DRIVE  
**Drive 45/157 Arms**



No UL certification

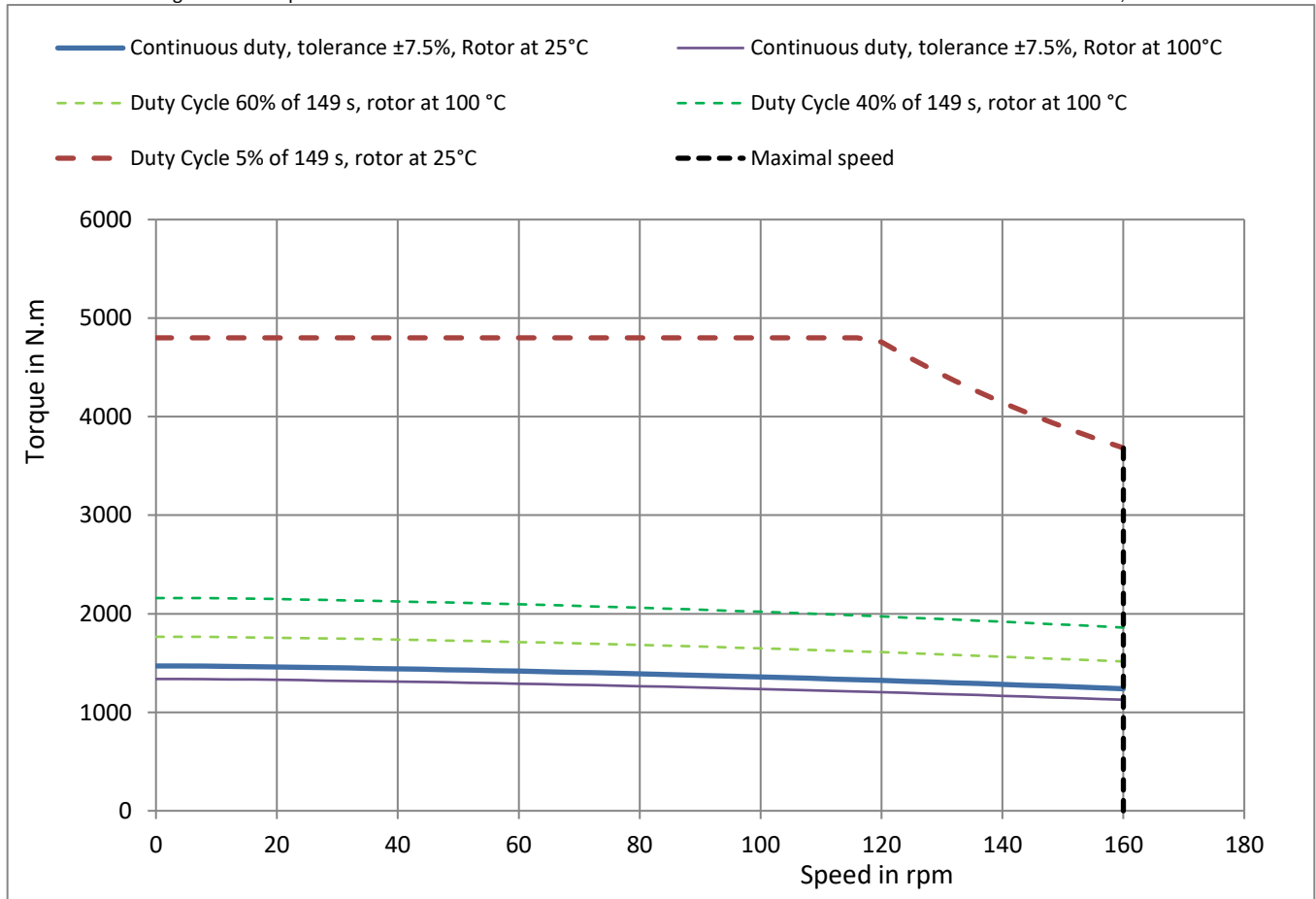
P <sub>n</sub>	<b>Rated power **</b>	20.8	<i>kW</i>	<b>Cooling type :</b> Natural Air Cooling Exchange Surface 1.2 m <sup>2</sup>
M <sub>n</sub>	<b>Rated torque **</b>	1240	<i>Nm</i>	
N <sub>n</sub>	<b>Rated speed</b>	160	<i>rpm</i>	
I <sub>n</sub>	<b>Rated current</b>	38.3	<i>A<sub>rms</sub></i>	
U <sub>n</sub>	<b>Rated voltage *</b>	346	<i>V<sub>rms</sub></i>	
UR	<b>Voltage of the mains</b>	400	<i>V<sub>rms</sub></i>	
U	DC voltage supply when motor is loaded	540	<i>V</i>	
M <sub>o</sub>	<b>Low speed torque **</b>	1470	<i>N.m</i>	<b>Environment :</b> Ambient temperature : 40°C MAX Altitude : < 1000 m Thermal class : F (according to IEC 60034-1)
I <sub>o</sub>	<b>Permanent current at low speed</b>	44.6	<i>A<sub>rms</sub></i>	
M <sub>p</sub>	Max. torque **	4800	<i>Nm</i>	
I <sub>p</sub>	Max. current	157	<i>A<sub>rms</sub></i>	
N <sub>p</sub>	Max. speed	160	<i>rpm</i>	
J	Rotor inertia	2.3	<i>kg.m<sup>2</sup></i>	Number of poles : 90 Electrical frequency @N <sub>p</sub> 120 Hz
Ke	Back emf constant at 1000 rpm (25°C)*	2070	<i>V<sub>rms</sub></i>	
Kt	Torque sensitivity (rotor 25°C)	33	<i>Nm/A<sub>rms</sub></i>	<b>Efficiency :</b> at rated torque : 91.2 % at 75% of rated torque : 92 %
R <sub>b</sub>	Winding resistance(25°C) *	0.452	<i>Ω</i>	
L	Winding inductance *	3.96	<i>mH</i>	

All data are given in typical values under standard conditions.

\* Phase to Phase

Characteristics are given for an optimal drive of the motor.

\*\* General tolerances ±7.5 %, rotor at 25°C





No UL certification

### Main characteristics

Rated power **	20.8	kW	Ps1
Peak power **	61.7	kW	Ps6
Low speed torque **	1470	N.m	Mo
Low speed peak torque **	4800	N.m	MoS6
Nominal speed (S1)	160	rpm	Nb
Max speed ****	160	rpm	Nmax
DC voltage supply when motor is loaded	540	Vdc	Ū
Permanent current at low speed	44.6	Arms	Io
S6 current at low speed	157	Arms	IoS6

### Mechanical parameters

Rotor inertia	2.3	kg.m <sup>2</sup>	J
Motor mass	--	kg	M
Maximum speed with Drive	160	rpm	Nmax
Maximum mechanical speed	-	rpm	Nmec

### Electrical parameters

Number of poles	90		
Winding resistance (25°C) *	0.452	Ω	Rb
Back EMF voltage/ 1000 rpm *	2070	Vrms / 1000 rpm	ke
Back EMF voltage / (rad/s) *	19.8	Vrms / (rad/s)	ku
Torque constant	33	N.m / Arms	Kt
Short circuit current	126	Arms	Icc
Inductance Lq (Back EMF voltage axis) *	3.96	mH	Lq
Inductance Ld *	4.03	mH	Ld
Optimal phasing at permanent current	10	electrical degree	ψo
Optimal phasing at S6 current	20	electrical degree	ψm

### Thermal parameters

Motor thermal resistance	0.0503	K/W	Rth
Motor thermal time constant	--	s	Tth
Winding thermal time constant	380	s	Tthw
Natural Air Cooling / Exchange Surface	1.2 m <sup>2</sup>		

Thermal class according to IEC 60034-1

F

\* Phase to phase

\*\* Tolerances ± 7.5% and rotor at 25°C

BRUSHLESS MOTOR  
**TKA306HM**  
 ELECTRONIC DRIVE  
**Drive 55/190 Arms**



No UL certification

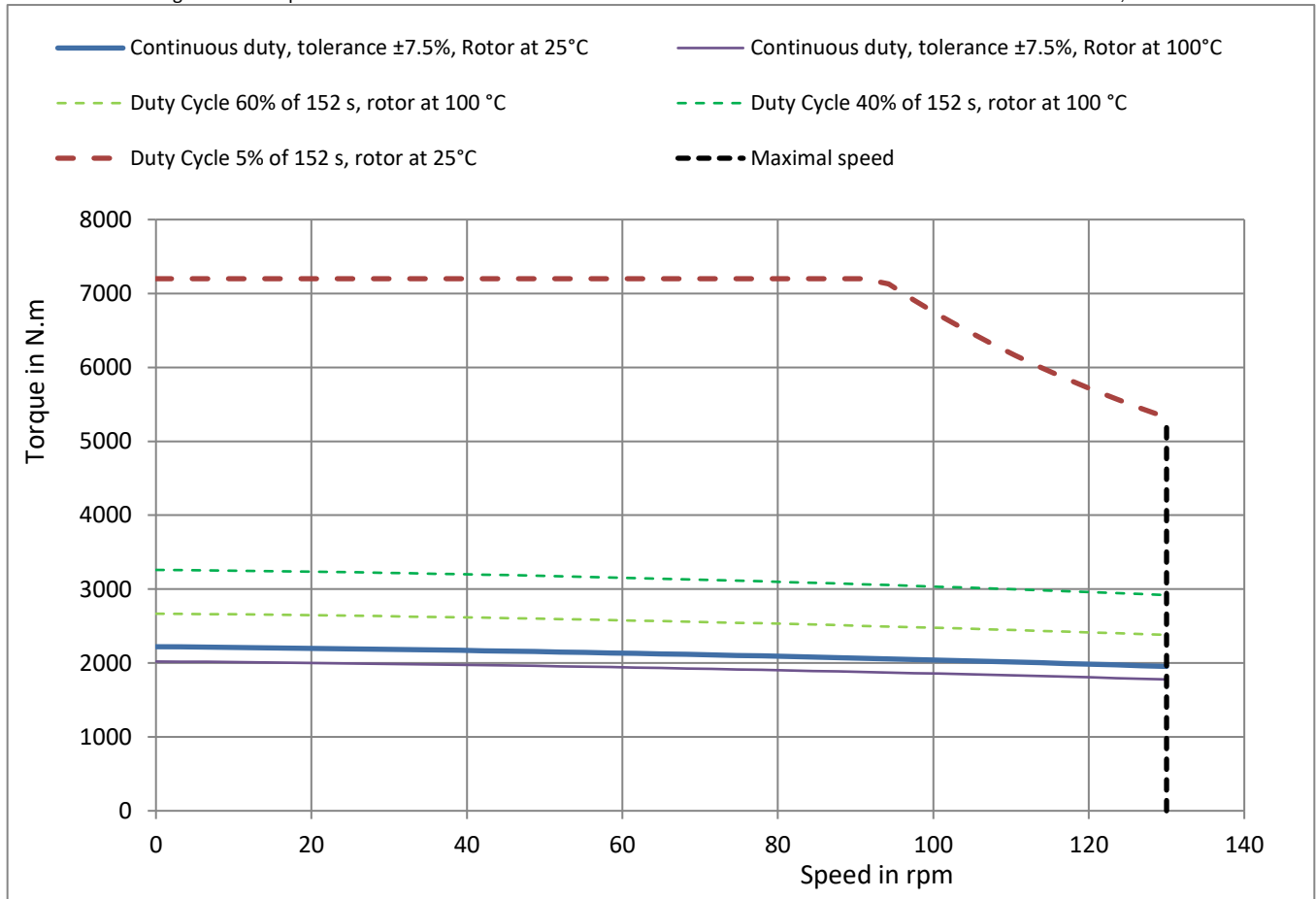
P <sub>n</sub>	<b>Rated power **</b>	26.6	<i>kW</i>	<b>Cooling type :</b> Natural Air Cooling Exchange Surface 1.7 m <sup>2</sup>
M <sub>n</sub>	<b>Rated torque **</b>	1950	<i>Nm</i>	
N <sub>n</sub>	<b>Rated speed</b>	130	<i>rpm</i>	
I <sub>n</sub>	<b>Rated current</b>	48.6	<i>A<sub>rms</sub></i>	
U <sub>n</sub>	<b>Rated voltage *</b>	352	<i>V<sub>rms</sub></i>	
U <sub>R</sub>	<b>Voltage of the mains</b>	400	<i>V<sub>rms</sub></i>	
U	DC voltage supply when motor is loaded	540	<i>V</i>	
M <sub>o</sub>	<b>Low speed torque **</b>	2220	<i>N.m</i>	<b>Environment :</b> Ambient temperature : 40°C MAX Altitude : < 1000 m Thermal class : F (according to IEC 60034-1)
I <sub>o</sub>	<b>Permanent current at low speed</b>	54.5	<i>A<sub>rms</sub></i>	
M <sub>p</sub>	Max. torque **	7200	<i>Nm</i>	
I <sub>p</sub>	Max. current	190	<i>A<sub>rms</sub></i>	
N <sub>p</sub>	Max. speed	130	<i>rpm</i>	
J	Rotor inertia	3.4	<i>kg.m<sup>2</sup></i>	
K <sub>e</sub>	Back emf constant at 1000 rpm (25°C)*	2550	<i>V<sub>rms</sub></i>	Number of poles : 90 Electrical frequency @N <sub>p</sub> 98 Hz <b>Efficiency :</b> at rated torque : 90.5 % at 75% of rated torque : 91.8 %
K <sub>t</sub>	Torque sensitivity (rotor 25°C)	40.7	<i>Nm/A<sub>rms</sub></i>	
R <sub>b</sub>	Winding resistance(25°C) *	0.424	<i>Ω</i>	
L	Winding inductance *	4.03	<i>mH</i>	

All data are given in typical values under standard conditions.

\* Phase to Phase

Characteristics are given for an optimal drive of the motor.

\*\* General tolerances ±7.5 %, rotor at 25°C





No UL certification

### Main characteristics

Rated power **	26.6	kW	Ps1
Peak power **	72.5	kW	Ps6
Low speed torque **	2220	N.m	Mo
Low speed peak torque **	7200	N.m	MoS6
Nominal speed (S1)	130	rpm	Nb
Max speed ****	130	rpm	Nmax
DC voltage supply when motor is loaded	540	Vdc	Ū
Permanent current at low speed	54.5	Arms	Io
S6 current at low speed	190	Arms	IoS6

### Mechanical parameters

Rotor inertia	3.4	kg.m <sup>2</sup>	J
Motor mass	--	kg	M
Maximum speed with Drive	130	rpm	Nmax
Maximum mechanical speed	-	rpm	Nmec

### Electrical parameters

Number of poles	90		
Winding resistance (25°C) *	0.424	Ω	Rb
Back EMF voltage/ 1000 rpm *	2550	Vrms / 1000 rpm	ke
Back EMF voltage / (rad/s) *	24.4	Vrms / (rad/s)	ku
Torque constant	40.7	N.m / Arms	Kt
Short circuit current	153	Arms	Icc
Inductance Lq (Back EMF voltage axis) *	4.03	mH	Lq
Inductance Ld *	4.1	mH	Ld
Optimal phasing at permanent current	10	electrical degree	ψo
Optimal phasing at S6 current	20	electrical degree	ψm

### Thermal parameters

Motor thermal resistance	0.0349	K/W	Rth
Motor thermal time constant	--	s	Tth
Winding thermal time constant	380	s	Tthw
Natural Air Cooling / Exchange Surface	1.7 m <sup>2</sup>		

Thermal class according to IEC 60034-1

F

\* Phase to phase

\*\* Tolerances ± 7.5% and rotor at 25°C

BRUSHLESS MOTOR  
**TKA402HP**  
 ELECTRONIC DRIVE  
**Drive 50/241 Arms**



No UL certification

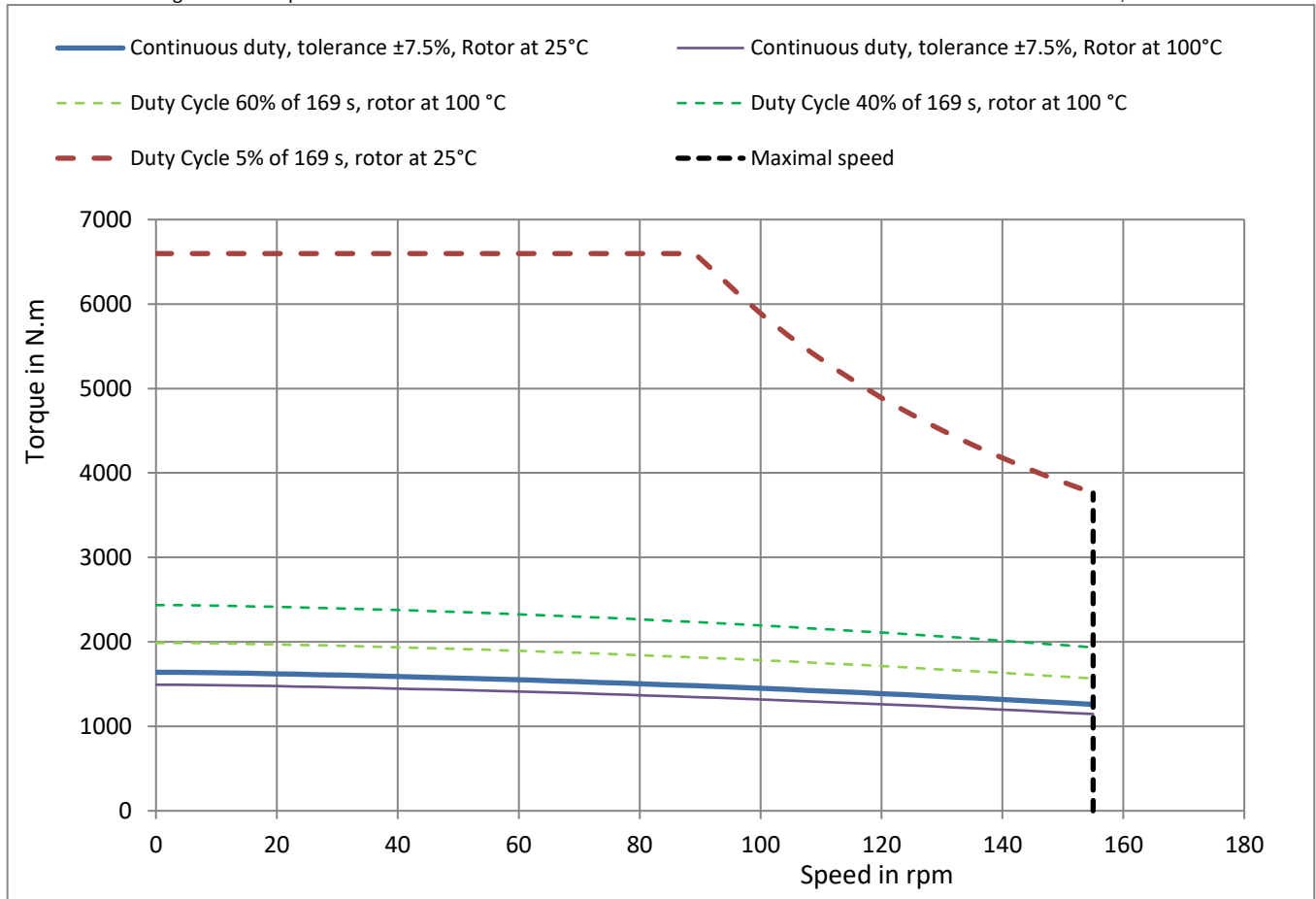
P <sub>n</sub>	<b>Rated power **</b>	20.4	<i>kW</i>	<b>Cooling type :</b> Natural Air Cooling Exchange Surface 0.94 m <sup>2</sup>
M <sub>n</sub>	<b>Rated torque **</b>	1260	<i>Nm</i>	
N <sub>n</sub>	<b>Rated speed</b>	155	<i>rpm</i>	
I <sub>n</sub>	<b>Rated current</b>	37.8	<i>A<sub>rms</sub></i>	
U <sub>n</sub>	<b>Rated voltage *</b>	344	<i>V<sub>rms</sub></i>	
UR	<b>Voltage of the mains</b>	400	<i>V<sub>rms</sub></i>	
U	DC voltage supply when motor is loaded	540	<i>V</i>	
M <sub>o</sub>	<b>Low speed torque **</b>	1640	<i>N.m</i>	<b>Environment :</b> Ambient temperature : 40°C MAX Altitude : < 1000 m Thermal class : F (according to IEC 60034-1)
I <sub>o</sub>	<b>Permanent current at low speed</b>	47.6	<i>A<sub>rms</sub></i>	
M <sub>p</sub>	Max. torque **	6600	<i>Nm</i>	
I <sub>p</sub>	Max. current	241	<i>A<sub>rms</sub></i>	
N <sub>p</sub>	Max. speed	155	<i>rpm</i>	
J	Rotor inertia	3.5	<i>kg.m<sup>2</sup></i>	
Ke	Back emf constant at 1000 rpm (25°C)*	2190	<i>V<sub>rms</sub></i>	Number of poles : 120 Electrical frequency @N <sub>p</sub> 155 Hz
Kt	Torque sensitivity (rotor 25°C)	34.5	<i>Nm/A<sub>rms</sub></i>	
R <sub>b</sub>	Winding resistance(25°C) *	0.337	<i>Ω</i>	<b>Efficiency :</b> at rated torque : 92.1 % at 75% of rated torque : 92.2 %
L	Winding inductance *	3.46	<i>mH</i>	

All data are given in typical values under standard conditions.

\* Phase to Phase

Characteristics are given for an optimal drive of the motor.

\*\* General tolerances ±7.5 %, rotor at 25°C





No UL certification

### Main characteristics

Rated power **	20.4	kW	Ps1
Peak power **	61.8	kW	Ps6
Low speed torque **	1640	N.m	Mo
Low speed peak torque **	6600	N.m	MoS6
Nominal speed (S1)	155	rpm	Nb
Max speed ****	155	rpm	Nmax
DC voltage supply when motor is loaded	540	Vdc	Ū
Permanent current at low speed	47.6	Arms	Io
S6 current at low speed	241	Arms	IoS6

### Mechanical parameters

Rotor inertia	3.5	kg.m <sup>2</sup>	J
Motor mass	--	kg	M
Maximum speed with Drive	155	rpm	Nmax
Maximum mechanical speed	-	rpm	Nmec

### Electrical parameters

Number of poles	120		
Winding resistance (25°C) *	0.337	Ω	Rb
Back EMF voltage/ 1000 rpm *	2190	Vrms / 1000 rpm	ke
Back EMF voltage / (rad/s) *	20.9	Vrms / (rad/s)	ku
Torque constant	34.5	N.m / Arms	Kt
Short circuit current	115	Arms	Icc
Inductance Lq (Back EMF voltage axis) *	3.46	mH	Lq
Inductance Ld *	3.49	mH	Ld
Optimal phasing at permanent current	10	electrical degree	ψo
Optimal phasing at S6 current	20	electrical degree	ψm

### Thermal parameters

Motor thermal resistance	0.0587	K/W	Rth
Motor thermal time constant	--	s	Tth
Winding thermal time constant	430	s	Tthw
Natural Air Cooling / Exchange Surface	0.94 m <sup>2</sup>		

Thermal class according to IEC 60034-1

F

\* Phase to phase

\*\* Tolerances ± 7.5% and rotor at 25°C

BRUSHLESS MOTOR  
**TKA404HR**  
 ELECTRONIC DRIVE  
**Drive 70/333 Arms**



No UL certification

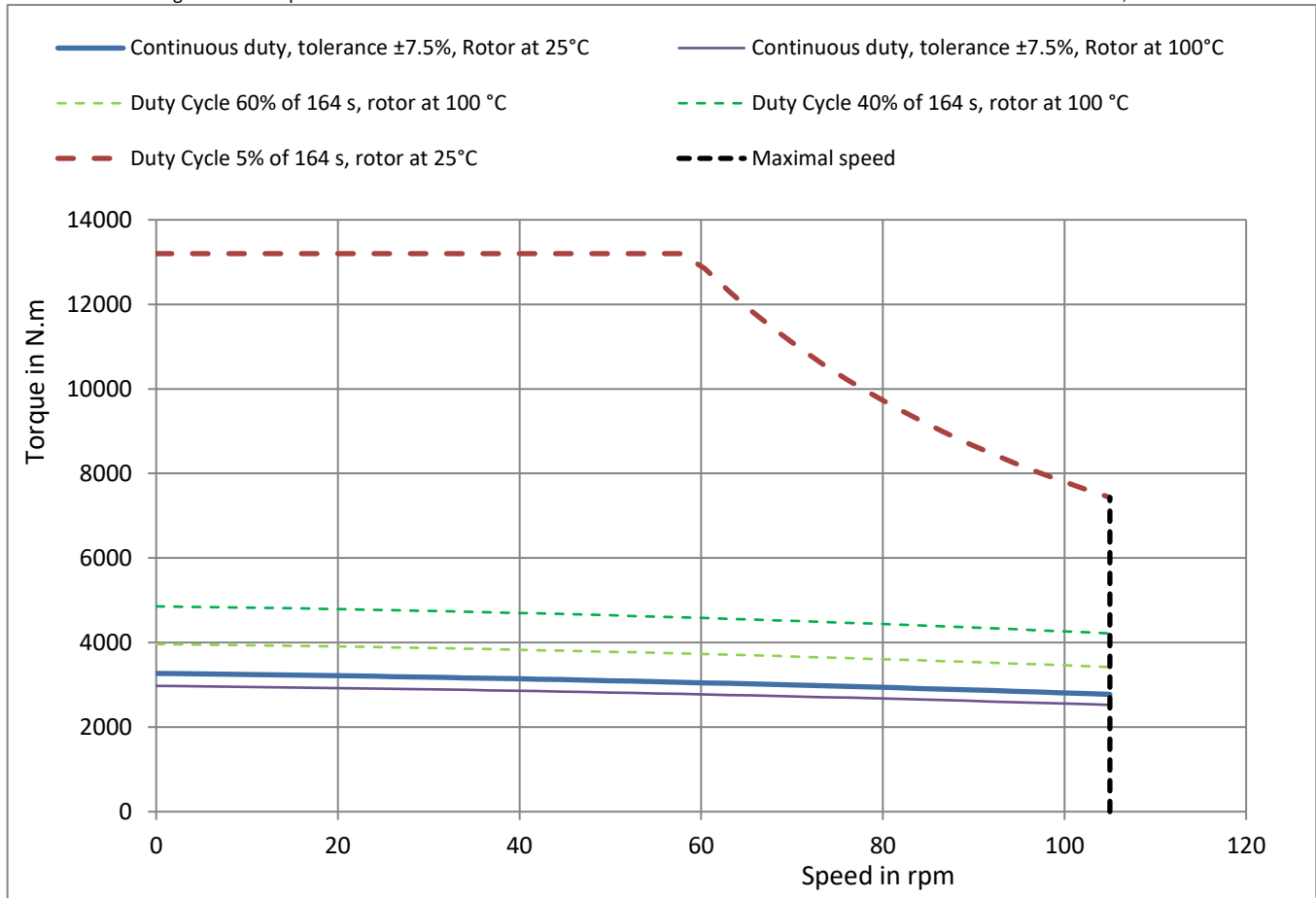
P <sub>n</sub>	<b>Rated power **</b>	30.5	<i>kW</i>	<b>Cooling type :</b> Natural Air Cooling Exchange Surface 1.7 m <sup>2</sup>
M <sub>n</sub>	<b>Rated torque **</b>	2770	<i>Nm</i>	
N <sub>n</sub>	<b>Rated speed</b>	105	<i>rpm</i>	
I <sub>n</sub>	<b>Rated current</b>	56.9	<i>A<sub>rms</sub></i>	
U <sub>n</sub>	<b>Rated voltage *</b>	346	<i>V<sub>rms</sub></i>	
U <sub>R</sub>	<b>Voltage of the mains</b>	400	<i>V<sub>rms</sub></i>	
U	DC voltage supply when motor is loaded	540	<i>V</i>	
M <sub>o</sub>	<b>Low speed torque **</b>	3270	<i>N.m</i>	<b>Environment :</b> Ambient temperature : 40°C MAX Altitude : < 1000 m Thermal class : F (according to IEC 60034-1)
I <sub>o</sub>	<b>Permanent current at low speed</b>	65.7	<i>A<sub>rms</sub></i>	
M <sub>p</sub>	Max. torque **	13200	<i>Nm</i>	
I <sub>p</sub>	Max. current	333	<i>A<sub>rms</sub></i>	
N <sub>p</sub>	Max. speed	105	<i>rpm</i>	
J	Rotor inertia	6.8	<i>kg.m<sup>2</sup></i>	Number of poles : 120 Electrical frequency @N <sub>p</sub> 105 Hz
K <sub>e</sub>	Back emf constant at 1000 rpm (25°C)*	3160	<i>V<sub>rms</sub></i>	
K <sub>t</sub>	Torque sensitivity (rotor 25°C)	49.8	<i>Nm/A<sub>rms</sub></i>	<b>Efficiency :</b> at rated torque : 90.9 % at 75% of rated torque : 91.9 %
R <sub>b</sub>	Winding resistance(25°C) *	0.319	<i>Ω</i>	
L	Winding inductance *	3.61	<i>mH</i>	

All data are given in typical values under standard conditions.

\* Phase to Phase

Characteristics are given for an optimal drive of the motor.

\*\* General tolerances ±7.5 %, rotor at 25°C





### Main characteristics

Rated power **	30.5	kW	Ps1
Peak power **	81.7	kW	Ps6
Low speed torque **	3270	N.m	Mo
Low speed peak torque **	13200	N.m	MoS6
Nominal speed (S1)	105	rpm	Nb
Max speed ****	105	rpm	Nmax
DC voltage supply when motor is loaded	540	Vdc	Ū
Permanent current at low speed	65.7	Arms	Io
S6 current at low speed	333	Arms	IoS6

### Mechanical parameters

Rotor inertia	6.8	kg.m <sup>2</sup>	J
Motor mass	--	kg	M
Maximum speed with Drive	105	rpm	Nmax
Maximum mechanical speed	-	rpm	Nmec

### Electrical parameters

Number of poles	120		
Winding resistance (25°C) *	0.319	Ω	Rb
Back EMF voltage/ 1000 rpm *	3160	Vrms / 1000 rpm	ke
Back EMF voltage / (rad/s) *	30.2	Vrms / (rad/s)	ku
Torque constant	49.8	N.m / Arms	Kt
Short circuit current	160	Arms	Icc
Inductance Lq (Back EMF voltage axis) *	3.61	mH	Lq
Inductance Ld *	3.63	mH	Ld
Optimal phasing at permanent current	10	electrical degree	ψo
Optimal phasing at S6 current	20	electrical degree	ψm

### Thermal parameters

Motor thermal resistance	0.0342	K/W	Rth
Motor thermal time constant	--	s	Tth
Winding thermal time constant	410	s	Tthw
Natural Air Cooling / Exchange Surface	1.7 m <sup>2</sup>		

Thermal class according to IEC 60034-1

F

\* Phase to phase

\*\* Tolerances ± 7.5% and rotor at 25°C



BRUSHLESS MOTOR  
**TKA406HP**  
 ELECTRONIC DRIVE  
**Drive 80/394 Arms**



No UL certification

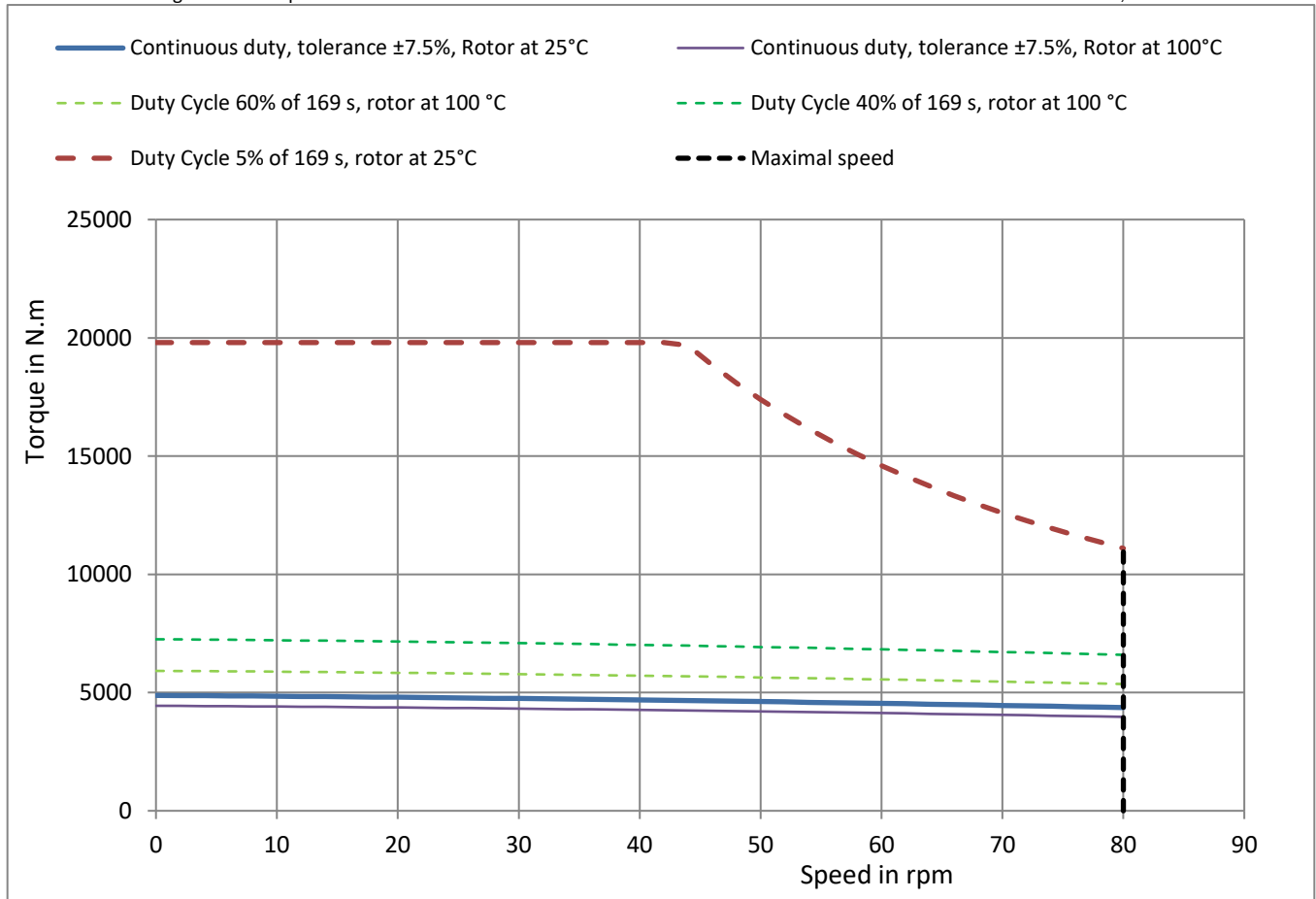
P <sub>n</sub>	<b>Rated power **</b>	36.6	<i>kW</i>	<b>Cooling type :</b> Natural Air Cooling Exchange Surface 2.4 m <sup>2</sup>
M <sub>n</sub>	<b>Rated torque **</b>	4370	<i>Nm</i>	
N <sub>n</sub>	<b>Rated speed</b>	80	<i>rpm</i>	
I <sub>n</sub>	<b>Rated current</b>	70.2	<i>A<sub>rms</sub></i>	
U <sub>n</sub>	<b>Rated voltage *</b>	341	<i>V<sub>rms</sub></i>	
UR	<b>Voltage of the mains</b>	400	<i>V<sub>rms</sub></i>	
U	DC voltage supply when motor is loaded	540	<i>V</i>	
M <sub>o</sub>	<b>Low speed torque **</b>	4880	<i>N.m</i>	<b>Environment :</b> Ambient temperature : 40°C MAX Altitude : < 1000 m Thermal class : F (according to IEC 60034-1)
I <sub>o</sub>	<b>Permanent current at low speed</b>	77.3	<i>A<sub>rms</sub></i>	
M <sub>p</sub>	Max. torque **	19800	<i>Nm</i>	
I <sub>p</sub>	Max. current	394	<i>A<sub>rms</sub></i>	
N <sub>p</sub>	Max. speed	80	<i>rpm</i>	
J	Rotor inertia	10.1	<i>kg.m<sup>2</sup></i>	
Ke	Back emf constant at 1000 rpm (25°C)*	4010	<i>V<sub>rms</sub></i>	Number of poles : 120 Electrical frequency @N <sub>p</sub> 80 Hz
Kt	Torque sensitivity (rotor 25°C)	63.1	<i>Nm/A<sub>rms</sub></i>	
R <sub>b</sub>	Winding resistance(25°C) *	0.318	<i>Ω</i>	<b>Efficiency :</b> at rated torque : 89.8 % at 75% of rated torque : 91.3 %
L	Winding inductance *	3.87	<i>mH</i>	

All data are given in typical values under standard conditions.

\* Phase to Phase

Characteristics are given for an optimal drive of the motor.

\*\* General tolerances ±7.5 %, rotor at 25°C





No UL certification

### Main characteristics

Rated power **	36.6	kW	Ps1
Peak power **	93	kW	Ps6
Low speed torque **	4880	N.m	Mo
Low speed peak torque **	19800	N.m	MoS6
Nominal speed (S1)	80	rpm	Nb
Max speed ****	80	rpm	Nmax
DC voltage supply when motor is loaded	540	Vdc	Ū
Permanent current at low speed	77.3	Arms	Io
S6 current at low speed	394	Arms	IoS6

### Mechanical parameters

Rotor inertia	10.1	kg.m <sup>2</sup>	J
Motor mass	--	kg	M
Maximum speed with Drive	80	rpm	Nmax
Maximum mechanical speed	-	rpm	Nmec

### Electrical parameters

Number of poles	120		
Winding resistance (25°C) *	0.318	Ω	Rb
Back EMF voltage/ 1000 rpm *	4010	Vrms / 1000 rpm	ke
Back EMF voltage / (rad/s) *	38.3	Vrms / (rad/s)	ku
Torque constant	63.1	N.m / Arms	Kt
Short circuit current	189	Arms	Icc
Inductance Lq (Back EMF voltage axis) *	3.87	mH	Lq
Inductance Ld *	3.9	mH	Ld
Optimal phasing at permanent current	10	electrical degree	ψo
Optimal phasing at S6 current	20	electrical degree	ψm

### Thermal parameters

Motor thermal resistance	0.0241	K/W	Rth
Motor thermal time constant	--	s	Tth
Winding thermal time constant	430	s	Tthw
Natural Air Cooling / Exchange Surface	2.4 m <sup>2</sup>		

Thermal class according to IEC 60034-1

F

\* Phase to phase

\*\* Tolerances ± 7.5% and rotor at 25°C

BRUSHLESS MOTOR  
**TKA40CHK**  
 ELECTRONIC DRIVE  
**Drive 120/578 Arms**



No UL certification

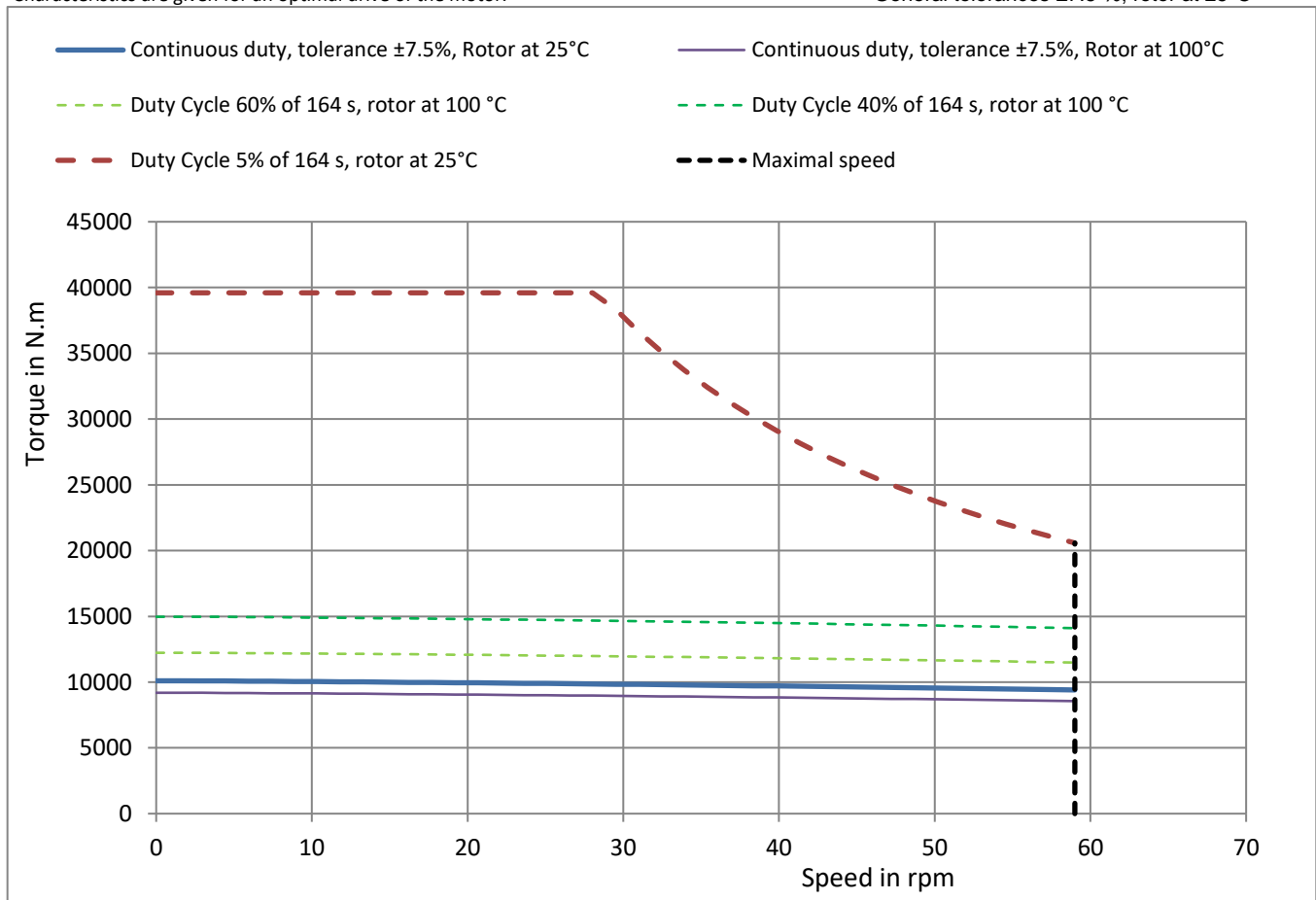
P <sub>n</sub>	<b>Rated power **</b>	58.1	<i>kW</i>	<b>Cooling type :</b> Natural Air Cooling Exchange Surface 4.6 m <sup>2</sup>
M <sub>n</sub>	<b>Rated torque **</b>	9400	<i>Nm</i>	
N <sub>n</sub>	<b>Rated speed</b>	59	<i>rpm</i>	
I <sub>n</sub>	<b>Rated current</b>	110	<i>A<sub>rms</sub></i>	
U <sub>n</sub>	<b>Rated voltage *</b>	358	<i>V<sub>rms</sub></i>	
UR	<b>Voltage of the mains</b>	400	<i>V<sub>rms</sub></i>	
U	DC voltage supply when motor is loaded	540	<i>V</i>	
M <sub>o</sub>	<b>Low speed torque **</b>	10100	<i>N.m</i>	<b>Environment :</b> Ambient temperature : 40°C MAX Altitude : < 1000 m Thermal class : F (according to IEC 60034-1)
I <sub>o</sub>	<b>Permanent current at low speed</b>	117	<i>A<sub>rms</sub></i>	
M <sub>p</sub>	Max. torque **	39600	<i>Nm</i>	
I <sub>p</sub>	Max. current	578	<i>A<sub>rms</sub></i>	
N <sub>p</sub>	Max. speed	59	<i>rpm</i>	
J	Rotor inertia	20	<i>kg.m<sup>2</sup></i>	Number of poles : 120 Electrical frequency @N <sub>p</sub> 59 Hz
Ke	Back emf constant at 1000 rpm (25°C)*	5470	<i>V<sub>rms</sub></i>	
Kt	Torque sensitivity (rotor 25°C)	86.3	<i>Nm/A<sub>rms</sub></i>	<b>Efficiency :</b> at rated torque : 86.8 % at 75% of rated torque : 89.6 %
R <sub>b</sub>	Winding resistance(25°C) *	0.291	<i>Ω</i>	
L	Winding inductance *	3.6	<i>mH</i>	

All data are given in typical values under standard conditions.

\* Phase to Phase

Characteristics are given for an optimal drive of the motor.

\*\* General tolerances ±7.5 %, rotor at 25°C





No UL certification

### Main characteristics

Rated power **	58.1	kW	Ps1
Peak power **	127	kW	Ps6
Low speed torque **	10100	N.m	Mo
Low speed peak torque **	39600	N.m	MoS6
Nominal speed (S1)	59	rpm	Nb
Max speed ****	59	rpm	Nmax
DC voltage supply when motor is loaded	540	Vdc	Ū
Permanent current at low speed	117	Arms	Io
S6 current at low speed	578	Arms	IoS6

### Mechanical parameters

Rotor inertia	20	kg.m <sup>2</sup>	J
Motor mass	--	kg	M
Maximum speed with Drive	59	rpm	Nmax
Maximum mechanical speed	-	rpm	Nmec

### Electrical parameters

Number of poles	120		
Winding resistance (25°C) *	0.291	Ω	Rb
Back EMF voltage/ 1000 rpm *	5470	Vrms / 1000 rpm	ke
Back EMF voltage / (rad/s) *	52.2	Vrms / (rad/s)	ku
Torque constant	86.3	N.m / Arms	Kt
Short circuit current	277	Arms	Icc
Inductance Lq (Back EMF voltage axis) *	3.6	mH	Lq
Inductance Ld *	3.62	mH	Ld
Optimal phasing at permanent current	10	electrical degree	ψo
Optimal phasing at S6 current	20	electrical degree	ψm

### Thermal parameters

Motor thermal resistance	0.0128	K/W	Rth
Motor thermal time constant	--	s	Tth
Winding thermal time constant	410	s	Tthw
Natural Air Cooling / Exchange Surface	4.6 m <sup>2</sup>		

Thermal class according to IEC 60034-1

F

\* Phase to phase

\*\* Tolerances ± 7.5% and rotor at 25°C